Accurate and Explainable Mortality Forecasting with the LocalGLMnet

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Insurance Data Science Conference 2023 - London (UK)

Mortality Forecasting

Introduction

- localGLMne Numerical Experiments
- Mortality is declining in most of developed countries;
- several mortality models have been proposed: Lee and Carter (1992), Ranshaw and Haberman (2006), Cairns, Blake and Dowd (2006), Plat (2009).



Figure: Italian mortality data (source: Human Mortality Database).

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- Numerical Experiments
- Deep Neural Networks (DNN) have been successfully applied to different tasks in actuarial science, including mortality modelling and forecasting. Several architectures have been investigated:
 - Fully Connected Networks: Hainaut (2019), Richman and Wüthrich (2021):
 - Recurrent Networks: Nigri et al. (2019), Perla et al. (2021), Lindholm and Palmborg (2022);
 - ▶ 1D Convolutional Networks: Perla et al. (2021), Scognamiglio (2022);
 - 2D Convolutional Networks: Wang et al. (2021), Schnurch and Korn (2022).
- Due to the complex structure of networks, it is difficult to determine the impact of inputs on the predictions.

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- Due to the complex structure of networks, it is difficult to determine the impact of inputs on the predictions.

Can we benefit from the predictive accuracy of DNN while maintaining an explainable model structure?

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localGLMnet Numerical Experiments Let $x \in \mathbb{R}^{q_0}$ be the vector of features, a fully connected (FC) layer of size $q_1 \in \mathbb{N}$ is a function

$$oldsymbol{z}:\mathbb{R}^{q_0}
ightarrow\mathbb{R}^{q_1},\qquadoldsymbol{x}\mapstooldsymbol{z}(oldsymbol{x})=(z_1(oldsymbol{x}),z_2(oldsymbol{x}),\ldots,z_{q_1}(oldsymbol{x}))^ op$$

Each component $z_j(x)$ is a non-linear function of x

$$\mathbf{x} \mapsto z_j(\mathbf{x}) = \phi\left(w_{j,0} + \sum_{l=1}^{q_0} w_{j,l} \mathbf{x}_l\right) = \phi\left(w_{j,0} + \langle \mathbf{w}_j, \mathbf{x} \rangle\right), \qquad j = 1, \dots, q_1,$$

where $\phi : \mathbb{R} \to \mathbb{R}$ is the activation function, $w_{j,l} \in \mathbb{R}$ represent the network parameters and $\langle \cdot, \cdot \rangle$ denotes the scalar product in \mathbb{R}^{q_0} .



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Neural Networks

Introduction

Numerical Experiments Deep neural networks compose multiple layers. For *d* layers of size $q = \{q_k\}_{1 \le k \le d} \in \mathbb{N}^d$, the mapping reads:

$$\mathbf{x} \mapsto \mathbf{z}^{(d:1)}(\mathbf{x}) \stackrel{\text{def}}{=} (\mathbf{z}^{(d)} \circ \cdots \circ \mathbf{z}^{(1)})(\mathbf{x}) \in \mathbb{R}^{q_d},$$

where $z^{(k)} : \mathbb{R}^{q_{k-1}} \to \mathbb{R}^{q_k}$. In the case of univariate response variable, the output of the network is:

$$\mathbf{x} \mapsto \mu_W(\mathbf{x}) \stackrel{\text{def}}{=} \Psi_W^{\text{FFN}}(\mathbf{x}) \stackrel{\text{def}}{=} g^{-1} \left(w_0^{(d+1)} + \sum_{l=1}^{q_d} w_l^{(d+1)} z_l^{(d:1)}(\mathbf{x}) \right),$$

 $g^{-1}(\cdot)$ is an inverse link function.



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Neural Networks

Introduction

Numerical Experiments The training of the NN induces the following optimisation:

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\underset{W}{\operatorname{arg\,min}} \mathcal{L}(y, \Psi_{W}^{\mathrm{FFN}}(x)),
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where

- $\mathcal{L}(\cdot)$ is the chosen loss function;
- W is the vector of the neural network parameters.



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Numerical Experiment Let Ψ_W be a neural network with output dimension equal to the input dimension q_0 :

$$\Psi_W: \mathbb{R}^{q_0} \to \mathbb{R}^{q_0}, \qquad \mathbf{x} \mapsto \Psi_W(\mathbf{x}),$$

having network weights W. The LocalGLMnet regression function is defined by

$$\mathbf{x} \mapsto \mu_{W,\beta_0}(\mathbf{x}) \stackrel{\text{def}}{=} \mathbf{g}^{-1}\left(\beta_0 + \boldsymbol{\beta}(\mathbf{x})^\top \mathbf{x}\right),$$

where $g : \mathbb{R} \to \mathbb{R}$ is the link function, $\beta_0 \in \mathbb{R}$, and $\beta(x) = \Psi_W(x)$.

- (1) If $\beta_j(\mathbf{x}) \equiv \beta_j$ is not feature dependent.
- (2) If $\beta_j(\mathbf{x}) \equiv 0$, term $\beta_j(\mathbf{x})x_j$ is dropped altogether.
- (3) If $\beta_j(\mathbf{x}) = \beta_j(x_j)$, term $\beta_j(x_j)x_j$ does not interact with any other terms $x_{j'}$, $j' \neq j$.
- (4) Interactions can be studied by considering the gradient of $\beta_j(x)$

$$\nabla \beta_j(\mathbf{x}) = \left(\partial_{x_1} \beta_j(\mathbf{x}), \dots, \partial_{x_{q_0}} \beta_j(\mathbf{x})\right)^\top \in \mathbb{R}^{q_0}$$

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Numerical Experiments

Let $X \in \mathbb{R}^{p \times q}$ be the matrix of input data, and Ψ_W be a neural network with output dimension equal to the input dimension $\mathbb{R}^{p \times q}$:

 $\Psi_W: \mathbb{R}^{p \times q} \to \mathbb{R}^{p \times q}, \qquad X \mapsto \Psi_W(X),$

having network weights W. The *multi-output LocalGLMnet* regression function is defined by

$$X \mapsto \mu_{W,\beta_0}(X) \stackrel{\text{def}}{=} g^{-1}\left(\beta_0 + \mathbf{1}_{\rho}^{\top}\left[B(X) \odot X\right]\right) \in \mathbb{R}^q,$$

where \odot is the Hadamard product, $\mathbf{1}_p = (1, \ldots, 1)^\top \in \mathbb{R}^p$, $g^{-1} : \mathbb{R} \to \mathbb{R}$ is applied in an element-wise manner, $\beta_0 \in \mathbb{R}^q$ is a vector of bias terms, and where we set regression attention matrix $B(X) = \Psi_W(X)$.

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Numerical Experiments

Let $\mathcal{X} = \{x \in \mathbb{N}_0 : 0 \le x \le \omega\}$ be the set of ages considered.

We denote:

- $m_{t+1}^{(i)} \in \mathbb{R}^{\omega+1}$ the vector mortality rates of a population *i* in year t+1;
- $M_{t-\tau,t}^{(i)} \in \mathbb{R}^{(\tau+1) \times (\omega+1)}$ the matrix of the mortality rates for all ages in the $\tau + 1$ past years.

We desire to learn the mapping

$$f: \mathbb{R}^{(\tau+1)\times(\omega+1)} \to \mathbb{R}^{\omega+1} \qquad M_{t-\tau,t}^{(i)} \mapsto \widehat{\boldsymbol{m}}_{t+1}^{(i)} = f\left(M_{t-\tau,t}^{(i)}\right).$$

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Numerical Experiments Applying the multi-output localGLM regression function:

$$\mathcal{M}_{t-\tau,t}^{(i)} \mapsto \mu_{W,\beta_0}(\mathcal{M}_{t-\tau,t}^{(i)}) \stackrel{\text{def}}{=} g^{-1} \left(\beta_0 + \mathbf{1}_p^\top \left[\mathcal{B}(\mathcal{M}_{t-\tau,t}^{(i)}) \odot \mathcal{M}_{t-\tau,t}^{(i)} \right] \right) \in \mathbb{R}^{\omega+1},$$

where $\beta_0 \in \mathbb{R}^{\omega+1}$ and $B(M_{t-\tau,t}^{(i)}) \in \mathbb{R}^{(\tau+1) \times (\omega+1)}$. Rewriting the model for a single age:

$$\widehat{m}_{j,t+1}^{(i)} = \left(\mu_{W,\beta_0}(M_{t-\tau,t}^{(i)}) \right)_j = g^{-1} \left(\beta_{0,j} + \beta_j (M_{t-\tau,t}^{(i)})^\top m_{(t-\tau,t),j}^{(i)} \right).$$

It can be rearranged as:

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$$g\left(\widehat{m}_{j,t+1}^{(i)}\right) = \beta_{0,j} + \sum_{s=0}^{\tau} \beta_{s,j}(M_{t-\tau,t}^{(i)}) m_{j,t-s}^{(i)},$$

that is AR(τ + 1), with varying coefficients derived from $M_{t-\tau,t}^{(i)}$.

How do we derive $B(M_{t-\tau,t}^{(i)})$?

Introduction

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Numerical Experiment We derive the attention coefficients $B(M_{t-\tau,t}^{(i)})$ by applying a **2D locally** connected layer to the matrix $M_{t-\tau,t}^{(i)}$.



where $W_{(s,x)} \in \mathbb{R}^{d_1 \times d_2}$ for $s = 0, 2, \dots, \tau, x = 0, 1, \dots, \omega$ are weight matrices.

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Numerical Experiments

- Data Source: Human Mortality Database:
 - Ages $\mathcal{X} = \{x \in \mathbb{N}_0 : 0 \le x < 100\};$
 - Years $T = \{t \in \mathbb{N} : 1950 \le t \le 2016\};$
 - Populations $|\mathcal{I}| = 76$.
- Data Partitioning:
 - Learning data $\mathcal{T}_{learn} = \{t \in \mathbb{N} : 1950 \le t \le 1999\};$
 - Test data $T_{test} = \{t \in \mathbb{N} : 2000 \le t \le 2016\}.$

The networks are trained by minimising:

$$\mathop{\arg\min}_{W}\mathcal{L}(W) = \mathop{\arg\min}_{W}\sum_{i}\sum_{x}\sum_{t}\left(m_{x,t}^{(i)} - \widehat{m}_{x,t}^{(i)}\right)^{2}.$$

where W denote the vector of network parameters.

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The attention coefficients $\beta_{s,x}(M_{t-\tau,t}^{(i)})$



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Numerical Experiments



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Forecasting Accuracy

Introductio

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Numerical Experiments

model	forecasting MSE	# parameters
LC	5.4659	18.698
LCCONV ¹	2.2936 (0.0282)	26.996
LocalGLMnet	2.1985 (0.0149)	26.000

Table: Average and standard deviation of the out-of-sample forecasting MSEs and number of trainable parameters of the LC, LCCONV, LocalGLMnet and models; the MSEs are multiplied by 10^4 .

¹Perla, F., Richman, R., Scognamiglio, S., & Wüthrich, M. V. (2021). Time-series forecasting of mortality rates using deep learning. Scandinavian Actuarial Journal; 2021(7), 572-598.

United States Mortality Database

Introduction

localGLMnet

Numerical Experiments

- Data Source: United States Mortality Database:
 - Ages $\mathcal{X} = \{ x \in \mathbb{N}_0 : 0 \le x < 100 \};$
 - Years $T = \{t \in \mathbb{N} : 1959 \le t \le 2017\};$
 - Populations $|\mathcal{I}| = 102$.
- Data Partitioning:
 - Learning data $\mathcal{T}_{learn} = \{t \in \mathbb{N} : 1959 \le t \le 1999\};$
 - Test data $\mathcal{T}_{test} = \{t \in \mathbb{N} : 2000 \le t \le 2017\}.$

We test three localGLMnet models:

- LocalGLMnet_HMD trained on the HMD data;
- LocalGLMnet_transfer trained on HMD data and the weights are further fine-tuned on the USMD data;
- LocalGLMnet_USMD directly trained on the USMD data.

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localGLMnet

Numerical Experiments

model	forecasting MSE	# pssarameters
LC	1.1848	24.684
LCCONV	0.4938 (0.0268)	27.061
$LocalGLMnet_HMD$	0.4075 (0.0102)	26.000
$LocalGLMnet_transfer$	0.2986 (0.0039)	26.000
$LocalGLMnet_USMD$	0.3134 (0.0100)	26.000

Table: Average and standard deviation of the forecasting MSEs and number of trainable parameters of the LC, LCCONV, LocalGLMnet_HMD, LocalGLMnet_transfer and LocalGLMnet_USMD models; the MSEs are multiplied by 10⁴.

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Conclusions

Introduction

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Numerical Experiments

- The LocalGLMnet model proposed by Richman and Wüthrich (2023) can be adapted to the time series forecasting task;
- accurate forecasts can be obtained without losing model explainability;
- transfer learning mechanisms can further improve forecasting accuracy.

For comments or suggestions:

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