

On Duration Effects in Non-Life Insurance Pricing

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The presentation is based on the paper

On Duration Effects in Non-Life Insurance Pricing

written together with Taariq Nazar (Stockholm University), to appear in the European Actuarial Journal

Background

- ▶ Data consists of triplets (Z, X, W) , where
 - ▶ Z corresponds to the response e.g. claim amount,
 - ▶ X is a vector of covariates,
 - ▶ W is an exposure weight e.g. policy duration
- ▶ Standard GLM assumptions

$$\mathbb{E}[Z | X, W] = W\mu(X), \text{ and } \text{Var}[Z | X, W] = W\sigma^2(X) \quad (\text{A1})$$

- ▶ ...more specifically: Tweedie

$$\text{Var}[Z | X, W] = W\varphi\mu(X)^\xi \quad (\text{A2})$$

where “ φ ” is the dispersion parameter

- ▶ Note that both (A1) and (A2) are linear in W

Background

Remarks

- ▶ Parameter estimation: the influence of W under (A1) is not obvious
- ▶ Under (A2): hard to estimate φ if $\mu(X)$ is badly specified (e.g. too rigid)

Background estimation

- ▶ Estimation of μ typically based on deviance loss functions, where the minimum is attained by the maximum likelihood estimator (MLE)
- ▶ We consider **Bregman deviance losses** (e.g. Poisson, and Gamma with fixed dispersion, under (A1))
- ▶ The deviance function for $Y = Z/W$ can be written as

$$D_{\text{Breg}}(Y, \mu) \propto Wd(Y, \mu),$$

where $d(Y, \mu)$ is the so-called unit deviance function, see e.g. Ohlsson & Johansson (2010), Wüthrich & Merz (2023)

Background estimation

- ▶ As discussed in Lindholm et al. (2023), the MLE for μ corresponds to the **empirical version** of the minimiser

$$\pi(X) \in \operatorname{argmin}_f \mathbb{E}[Wd(Y, f(X))], \quad (1)$$

where the minimisation is over suitable X -measurable functions f (see ref. for details)

- ▶ As shown in Lindholm et al. (2023), the population minimiser $\pi(X)$ is given by

$$\pi(X) = \frac{\mathbb{E}[Z | X]}{\mathbb{E}[W | X]}, \quad (2)$$

which does not assume (A1) and does not rely on any specific assumptions regarding the dependence between, Z , X , and W

Background estimation

Remarks

- ▶ From (2) it is clear that $\pi(X)$ will differ from $\mu(X)$ unless assumption (A1) is satisfied
- ▶ Given a reasonably well specified model, the above suggests that the MLE will be a consistent estimator of $\pi(X)$, which may, or may not, coincide with $\mu(X)$
- ▶ Note that $\pi(X)$ corresponds to the duration adjusted actuarially fair premium, since $\pi(X)$ satisfies the relation

$$\mathbb{E}[W\pi(X) | X] = \mathbb{E}[Z | X]$$

Background estimation

Note that

- ▶ Consistency relies on that we know that the functional form of the true model is a GLM (or some other model class)
- ▶ In practice the true model is unknown, and a misspecified model for $\mathbb{E}[Z | X]$ will lead to local bias, see e.g. Lindholm et al. (2023) and Wüthrich & Ziegel (2023)
- ▶ Local bias will contaminate estimation of the dispersion parameter φ

Estimators and asymptotics

Estimators and asymptotics

- ▶ Focus will be on estimating the mean function for a specific covariate vector $X = x$, without assuming any specific functional form of $\mu(X)$
- ▶ Given sufficiently many observations of $X = x$, we may estimate $\mu(x)$ as a parameter
- ▶ This is a reasonable assumption when we consider the situation of letting the sample size tend to infinity

Estimators and asymptotics

Proposition 1

Consider an i.i.d. sample $(Z_i, X_i, W_i)_{i=1}^m = (Z_i, x, W_i)_{i=1}^m$ and define $Y_i := Z_i/W_i$. The estimator $\hat{\mu}_m(x)$ that minimises the duration weighted Bregman deviance is given by

$$\hat{\mu}_m(x) = \frac{\hat{\mathbb{E}}_m[Z | X = x]}{\hat{\mathbb{E}}_m[W | X = x]},$$

where

$$\hat{\mathbb{E}}_m[Z | X = x] := \frac{1}{m} \sum_{i=1}^m Z_i, \quad \text{and} \quad \hat{\mathbb{E}}_m[W | X = x] := \frac{1}{m} \sum_{i=1}^m W_i,$$

for which it holds that

$$\hat{\mu}_m(x) \xrightarrow{p} \frac{\mathbb{E}[Z | X = x]}{\mathbb{E}[W | X = x]}, \quad \text{as } m \rightarrow \infty.$$

Estimators and asymptotics

Remarks (more in the paper)

- ▶ Proposition 1 does not assume
 - ▶ independence between Z and W
 - ▶ that the true data belongs to an EDF with expectation and variance being linear in W
- ▶ The predictor $\hat{\mu}_m$ in Proposition 1 is always asymptotically actuarially fair in the sense of π from (2)
...but π is not guaranteed to equal μ unless (A1) hold!

Estimators and asymptotics

Dispersion modelling

- ▶ Above we have seen that $\mathbb{E}[Z | X]$ and $\mathbb{E}[W | X]$ appeared as limiting objects
- ▶ When discussing dispersion and variation we will encounter

$$\text{Var}[Z | X] = \mathbb{E}[\text{Var}[Z | X, W]] + \text{Var}[\mathbb{E}[Z | X, W]],$$

or the corresponding expressions under Tweedie assumptions

- ▶ We will focus on **Pearson estimators** of φ :

$$\hat{\varphi}_m^P(x) := \frac{1}{m-1} \sum_{i=1}^m \frac{W_i (Y_i - \hat{\mu}_m(x))^2}{\hat{\mu}_m^\xi(x)} \quad (3)$$

...since there is trouble with consistency of deviance based estimators, see Lindholm & Nazar (2024)

Estimators and asymptotics

Proposition 2

Given an i.i.d. sample $(Z_i, X_i, W_i)_{i=1}^m = (Z_i, x, W_i)_{i=1}^m$ it holds that

$$\widehat{\varphi}_m^P(x) \xrightarrow{P} \varphi^{*,P}(x) = \overline{\varphi}(x) - \frac{\mathbb{E}[W | X = x]^{\xi-1}}{\mathbb{E}[Z | X = x]^{\xi}} \text{Cov} \left[\frac{Z^2}{W}, W \mid X = x \right],$$

as $m \rightarrow \infty$, where

$$\overline{\varphi}(x) := \frac{\mathbb{E}[W | X = x]^{\xi-1} \text{Var}[Z | X = x]}{\mathbb{E}[Z | X = x]^{\xi}}. \quad (4)$$

If the underlying data generating process agrees with moment assumptions (A1) and (A2) then $\varphi^{*,P}(x) = \varphi(x)$ and $\overline{\varphi}(x) > \varphi(x)$.

Estimators and asymptotics

Remarks

- ▶ Observing $\hat{\varphi}^{*,P}(x) \geq \hat{\varphi}(x)$ indicates violation of (A1) and (A2), see Lindholm & Nazar (2024)
- The same conclusions hold true if we observe $\hat{\varphi}^{*,P} \geq \hat{\varphi}(x)$
- ▶ The plug-in variance of Z based on $\hat{\varphi}^{*,P}(x)$ is only guaranteed to be consistent under (A1) and (A2), see Lindholm & Nazar (2024)
- An alternative to a plug-in variance estimator:

$$\widehat{\text{Var}}_m[Z | X = x] := \frac{1}{m-1} \sum_{i=1}^m (Z_i - \underbrace{\hat{\mathbb{E}}_m[W | X = x] \hat{\mu}_m(x)}_{\hat{\mathbb{E}}_m[Z|X=x]})^2 \quad (5)$$

which is consistent without assuming (A1) and (A2)!

Numerical illustrations

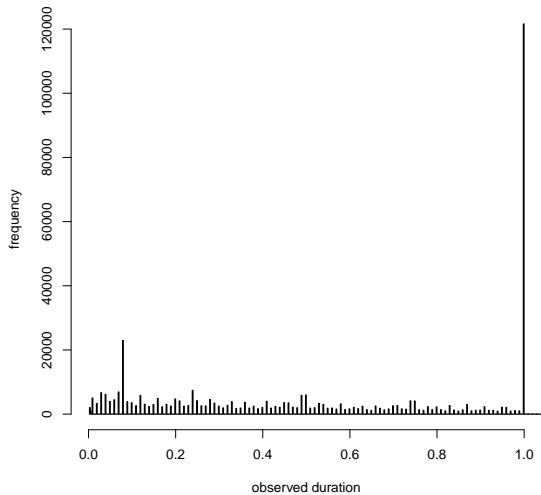
Setup

- ▶ Real insurance data: `freMTPLfreq`, see `CASdatasets`, and see Lindholm et al. (2023) for other examples
- ▶ Will use a Poisson GBM-model with linear weights in W , all standard parameters except tree depth, which is set to 2
- ▶ Optimal number of trees: 192

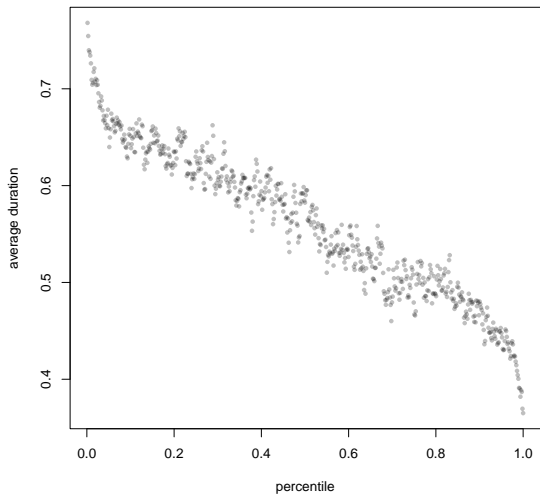
Model evaluation

- ▶ Use the $(\hat{\mu}(x_i))_{i=1}^n$ -predictions from the GBM and order these
- ▶ This gives us ordered $x_{(i)}$:s such that $\hat{\mu}(x_{(i)})$ corresponds to the i th largest prediction
- ▶ The ordered data set is split into $k = 200$ equally sized bins used to evaluate local performance

Numerical illustrations



Numerical illustrations



Numerical illustrations

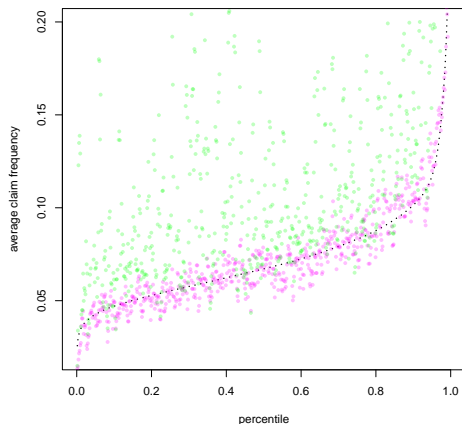


Figure: Dotted line: $\hat{\mu}(x)$; Purple dots:

$\hat{\pi}(x) := \frac{\hat{\mathbb{E}}[Z | X = x]}{\hat{\mathbb{E}}[W | X = x]}$; Green dots: $\hat{\mathbb{E}}[Y | X = x]$

Numerical illustrations

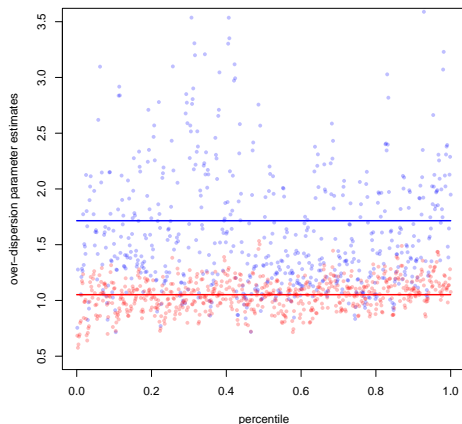


Figure: Blue dots: $\hat{\varphi}^P(x)$; Blue line: $\hat{\varphi}^P$; Red dots: $\hat{\varphi}(x)$; Red line: average of the $\hat{\varphi}(x)$ s

Numerical illustrations

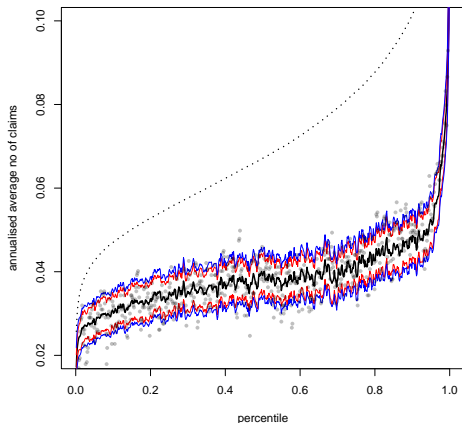


Figure: Black solid line: duration adjusted plug-in est. of $\mathbb{E}[Z | X = x]$;
Grey dots: $\hat{\mathbb{E}}[Z | X = x]$; Blue lines: plug-in est. of $\sqrt{\text{Var}[Z | X = x]}$;
Red lines: $\sqrt{\widehat{\text{Var}[Z | X = x]}}$; Dashed line: $\hat{\mu}(x)$

Numerical illustrations

Conclusions

- ▶ The dependence between Z and W matters in the bias calculations – supported by real data
- ▶ In the real data example the plug-in standard deviation variance **is on average 30% larger** than the corresponding local sample standard deviation using (5)
- ▶ This can be compared with that the using $\sqrt{\hat{\varphi}^P} \approx \sqrt{1.70} \approx 1.30$ instead of $\hat{\varphi} = \widehat{\text{Var}}[Z | X = x] / \widehat{\mathbb{E}}[Z | X = x] \approx 1.05$
- ▶ **Analysis “Trick”**: use the original predictor for risk ordering, and use simple sample variance estimators locally

References I

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